

Applied Nonlinear Control Slotine Solution Manual

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LYAPUNOV STABILITY THEORY:

Given a control system, the first and most important question about its various properties is whether it is stable, because an unstable control system is typically useless and potentially dangerous. Qualitatively, a system is described as stable if starting the system somewhere near its desired operating point implies that it will stay around the point ever after. Every control system, whether linear or nonlinear, involves a stability problem which should be carefully studied.

The most useful and general approach for studying the stability of nonlinear control systems is the theory introduced in the late 19th century by the Russian mathematician Alexandr Mikhailovich Lyapunov. Lyapunov's work, *The General Problem of Motion Stability*, includes two methods for stability analysis (the so-called linearization method and direct method) and was published in 1892. The linearization method draws conclusions about a nonlinear system's local stability around an equilibrium point from the stability properties of its linear approximation. The direct method is not restricted to local motion, and determines the stability properties of a nonlinear system by constructing a scalar "energy-like" function for the system and examining the function's time variation.

Slotine and Li, Applied Nonlinear Control

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